

Notice of References Cited	Application/Control No. 10/689,924	Applicant(s)/Patent Under Reexamination GALIBRAITH, JOHN	
	Examiner McDieunel Marc	Art Unit 3661	Page 1 of 1

U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
	A	US-6,906,639	06-2005	Lemelson et al.	340/903
	B	US-6,553,130	04-2003	Lemelson et al.	382/104
	C	US-6,487,500	11-2002	Lemelson et al.	701/301
	D	US-6,275,773	08-2001	Lemelson et al.	701/301
	E	US-5,983,161	11-1999	Lemelson et al.	701/301
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	J	US-			
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	L	US-			
	M	US-			

FOREIGN PATENT DOCUMENTS

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NON-PATENT DOCUMENTS

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)
	U	Yagi et al., Map-based navigation for a mobile robot with omnidirectional image sensor COPIS, 1995, IEEE, pg. 634-648
	V	Yagi et al., Estimating location and avoiding collision against unknown obstacles for the mobile robot using omnidirectional image sensor COPIS, 1991, IEEE, pg. 909-914
	W	Yagi et al., Map-based navigation for the mobile robot using omnidirectional image sensor COPIS, 1992, IEEE, pg.47-52
	X	Coombs et al., Real-time obstacle avoidance using central flow divergence, and peripheral flow, 1998, IEEE, pg. 49-59

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.